

Machine Learning Studies of JET Disruption

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IEA Workshop: Theory & Simulation of Disruptions
Princeton Plasma Physics Laboratory
Princeton, NJ

July 13-15, 2015

Collaborative contributions from the JET EUROfusion Disruptions Studies Team (J. Vega, A. Murari, et al.) and from Jong Choi of the Oak Ridge National Laboratory ORNL are gratefully acknowledged

US/EU Statistical Disruption Studies on JET [Joint European Torus]

Situation Analysis:

- **Most critical problem for MFE:** avoid/mitigate large-scale major disruptions
 - **Approach:** Use of big-data-driven statistical/machine-learning predictions for the occurrence of disruptions in JET
 - **Current Status:** ~ 6 years of R&D results (led by JET) using SVM-based ML on zero-D time trace data executed on modern clusters yielding ~ reported success rates ranging from 80 up to 95% for JET, BUT > 98% with false alarm rate < 2.5% actually needed for ITER (Reference – P. DeVries, et al., June 2015)
 - **PPPL Team Goals include:**
 - (i) improve physics fidelity via development of new ML multi-D, time-dependent software including better classifiers;
 - (ii) develop “portable” predictive software beyond JET to other devices and eventually ITER; and
 - (iii) enhance execution speed of disruption analysis for very large datasets via deployment on HPC leadership facilities
- NOTE:** → EUROfusion JET leadership has formally agreed to provide PPPL/PU with collaborative access to its huge disruption-relevant multi-dimensional data base that has yet to be analyzed.

CLASSIFICATION

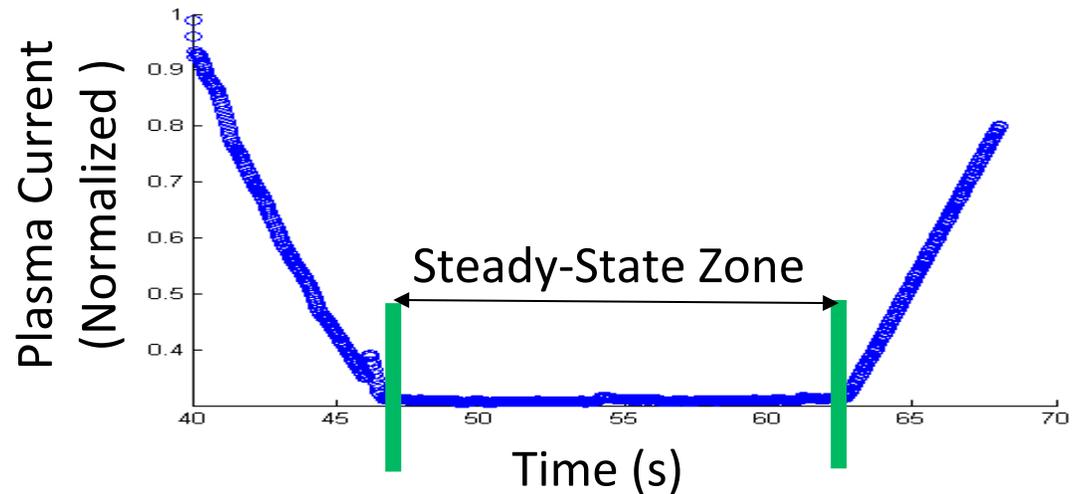
- Disruption Prediction is a “Binary Classification Problem:
 - *Disruptive or Non-Disruptive*
- Machine learning techniques for classification are Supervised
 - Our approach as physics domain scientists is to combine the considerable knowledge base of observationally validated information with advanced statistical predictive methods such as Machine Learning (ML)
 - ➔ Approach: examine relevant data base
 - Use training set to generate a model
 - Use trained model to classify new samples
 - Targeted multi-dimensional data analysis will require new signal representations other than current mean and std [*standard deviation of positive FFT spectrum (excluding first component)*]

Selecting Data From the Signals

Example*: Plasma Current

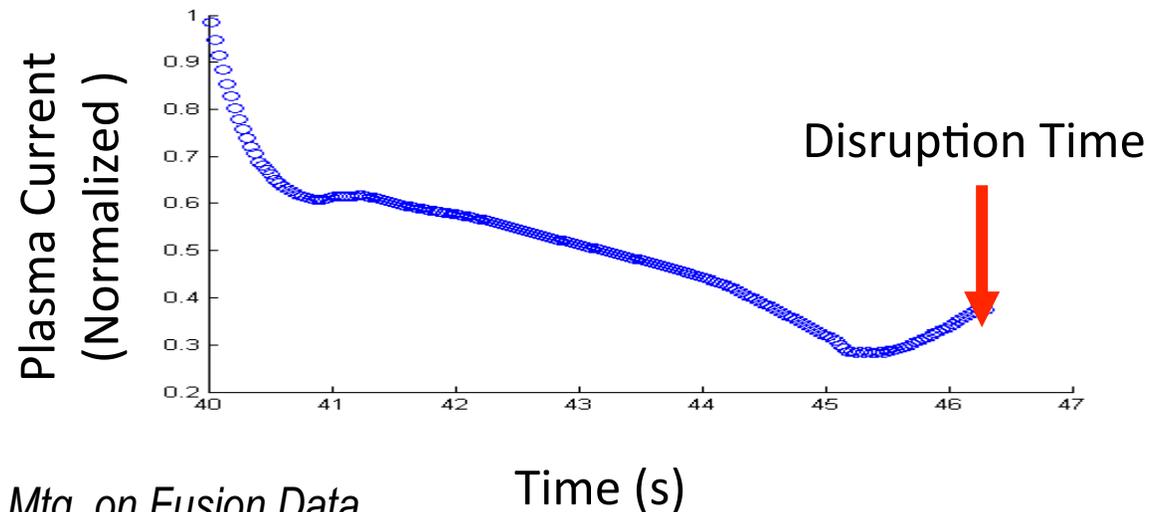
Non-Disruptive Signal:

Selecting non-disruptive points from the steady-state zone



Disruptive Signal:

Selecting disruptive points 64, 128, and 256 ms before disruption



Ref. → *S. Talabzadeh, et al. IAEA Tech. Mtg. on Fusion Data Processing, Validation, & Analysis, June 1-3, '15, Nice, France*

Feature Extraction Process

- Reduce data set to form “feature vectors” $\{x_i, y_i\}$
- Consider combination of signals to describe plasma:

$$\mathbf{x} \in \mathbb{R}^d$$

with

$$d = 14$$

7 signals* x 2 representations+

$$y \in \{+1, -1\}$$

{disruptive, non-disruptive state}

*Signals:

- (1) Plasma current [A]
- (2) Mode lock amplitude [T]
- (3) Plasma density [m^{-3}]
- (4) Radiated power [W]
- (5) Total input power [W]
- (6) d/dt Stored Diamagnetic Energy [W]
- (7) Plasma Internal Inductance

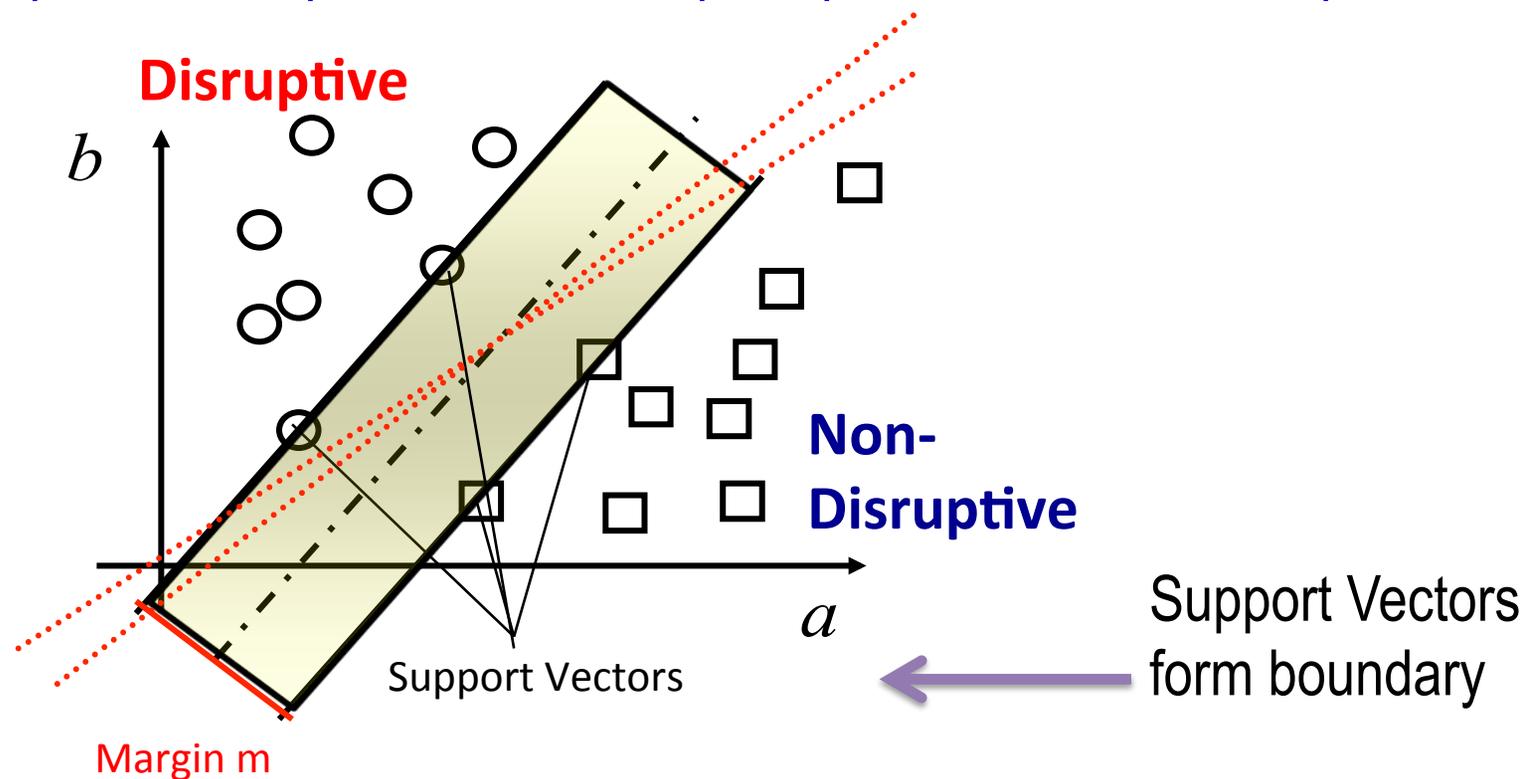
+Representations (set of 32 samples at 1 kHz):

- (1) Mean
- (2) Standard deviation of positive FFT spectrum
(excluding first component)

*Each signal normalized to [0,1]
over entire data set

SVM Picture

Decision Function $f(x)$ as hyperplane with a normal w and displacement b to separate disruptive & non-disruptive points in the feature space

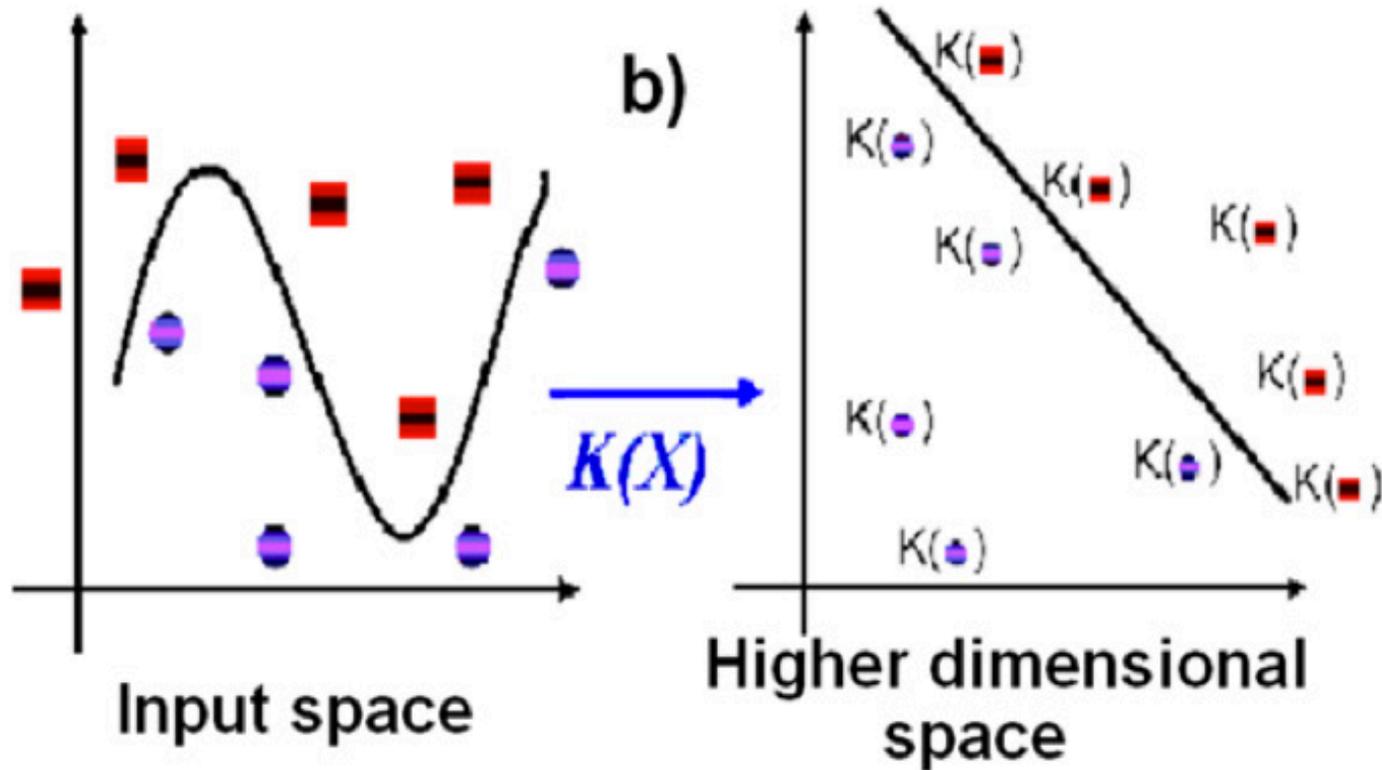


TASK: find hyperplane separating “disruptive” and “non-disruptive” states with widest possible margin

$$f(\mathbf{x}) = \mathbf{w} \cdot \mathbf{x} + b = 0$$

BUT, real data is NOT linearly separable !

SVM Picture (continued)



→ $K(x)$ represents function needed to map data to a higher dimensional space where it can actually be separated

Reference #2: G.A. Rattá et al. Nuclear Fusion, 50 (2010)

$$f(\mathbf{x}) = \mathbf{w} \cdot \varphi(\mathbf{x}) + b = 0$$

SVM Decision Function

After solving the optimization problem, classify new data using:

$$f_D(\mathbf{x}) = \sum_i \alpha_i y_i K(\mathbf{x}_i, \mathbf{x})$$

Lagrange Multipliers

Support Vectors

Kernel Function
(e.g., Radial Basis Function/Gaussian)

Assess accuracy in terms of:

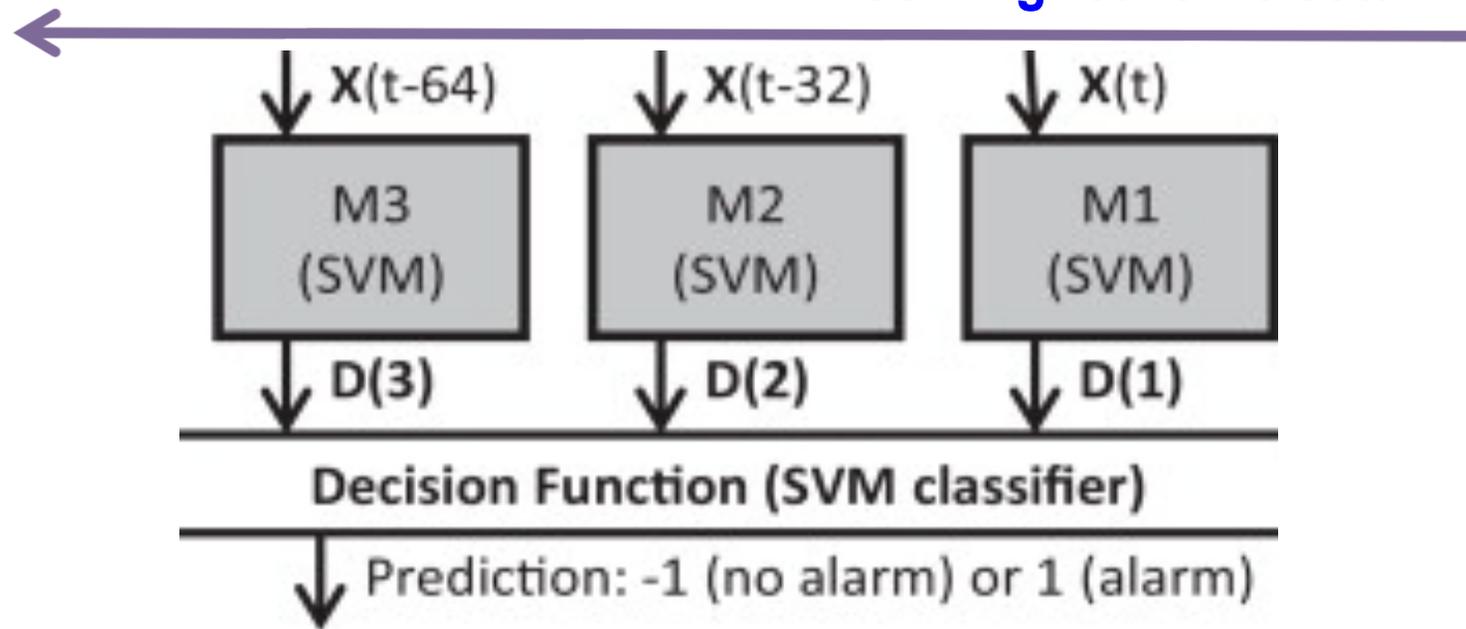
- Correct predictions
- Missed alarms
- False alarms

Multi-tiered SVM

(separate SVM models trained for separate consecutive time intervals preceding disruption)

(applied to APODIS Code developed by J. Vega, et al.)

Incoming real-time data



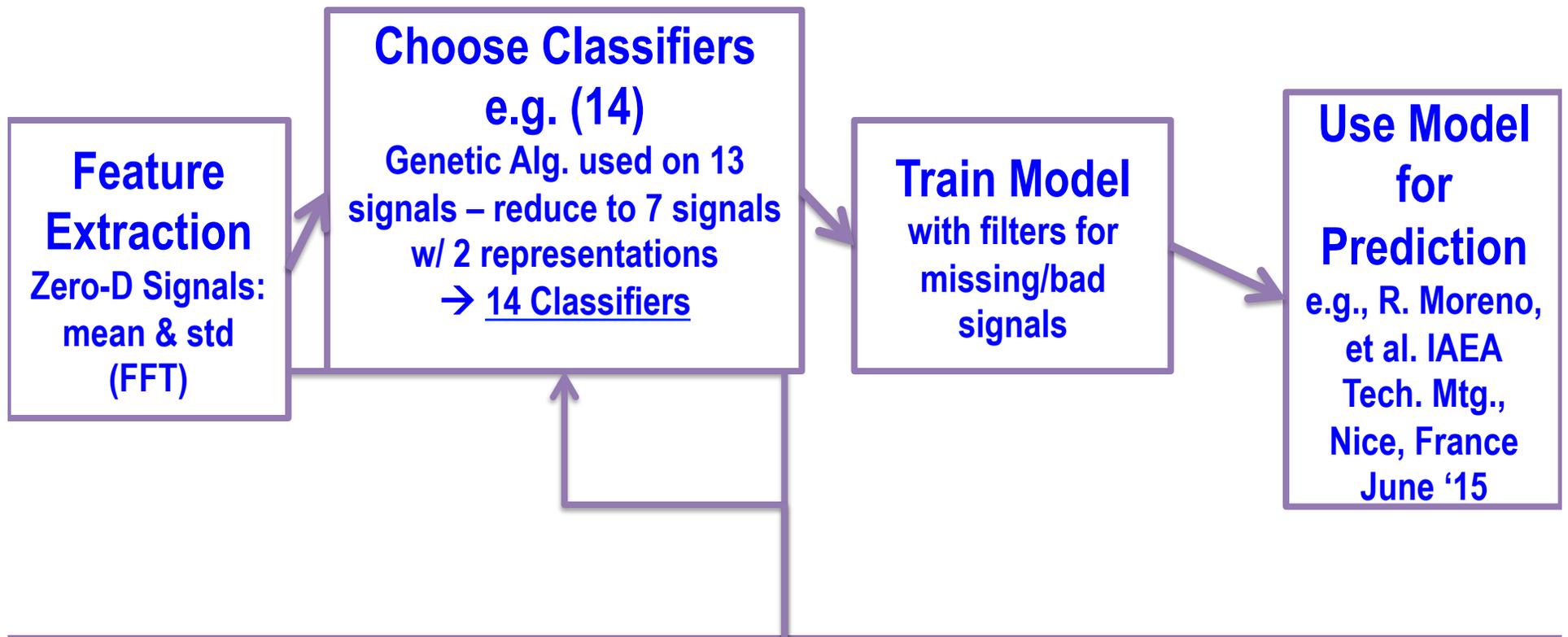
1st Tier: Three models trained separately on sequential data with RBF (Gaussian) kernel *(Note: up to 8 models were considered)*

2nd Tier: Trained with linear kernel on combined Tier 1 outputs

Reference: J. Vega et al. *Fusion Engineering and Design*, **88** (2013)

[APODIS → “Advanced Predictor of Disruptions”]

ML SVM Workflow



Moving forward, PPPL team will focus on multi-dimensional (instead of present zero-D time trace) signals

e.g. radial temperature profile

Many interesting possibilities for more efficient, physics-motivated choices of classifiers

ML Predictive Challenges & Opportunities

- CHALLENGE: SVM results at JET currently delivers in range of 80% to 95% accuracy, but *need to consistently achieve > 98% for reliable ITER operation*
- PPPL FOCUS: Improve predictive performance by enhancing physics fidelity following “Supervised ML Theme”
- *Function of time + spatial dimensions, including profile/gradient information*
 - Serve as inputs for regression-type formulation of stability thresholds for improving physics-based classifiers
 - Investigation of parametric scaling trends
 - Explore multi-dimensional signals with associated introduction of much larger/more complex database
 - Explore inclusion of threshold conditions for key disruption precursors (currently NOT included in SVM classifiers) such as Neoclassical Tearing Modes (NTM)

ML Predictive Challenges & Opportunities

- Portability Challenge for ML Predictive Software (beyond JET):
 - First investigate applicability to NSTX/NSTX-U disruption database, and then move on to others (DIII-D, ASDEX, EAST, KSTAR,) → ultimately leading to ITER
- Alternative Methods to SVM:
 - Deterministic Annealing (collaboratively with J. Choi of ORNL)
 - Can be used in parallel with SVM or used to improve choice of classifiers as part of SVM workflow
- “Deep Learning” Algorithms
 - For feature selection approaches with broader scope than current Genetic Algorithms
- Broader Applicability of ML Methods (developed for disruption predictions)
 - e.g., apply to predictions of other important “binary” type fusion physics phenomena such as “L to H” transitions
- Deployment of more advanced ML software engaging very large dataset investigations on HPC leadership hardware

Disruption Data Subset

# Shots	Disruptive	Nondisruptive	Totals
Carbon Wall	324	4029	4353
Beryllium Wall	185	1036	1221
Totals	509	5065	5574

JET produces ~
Terabyte (TB) of
data per day

Sample Signals (0-D time trace)	Data Size (GB)
Plasma Current	1.8
Mode Lock Amplitude	1.8
Plasma Density	7.8
Radiated Power	30.0
Total Input Power	3.0
d/dt Stored Diamagnetic Energy	2.9
Plasma Internal Inductance	3.0

~55 GB data
collected from
each JET shot

→ Well over 35 TB total
amount with multi-
dimensional data yet to
be analyzed

**JET
Disruption
Shot
#82499**

**~ 1 second
before
thermal
quench**

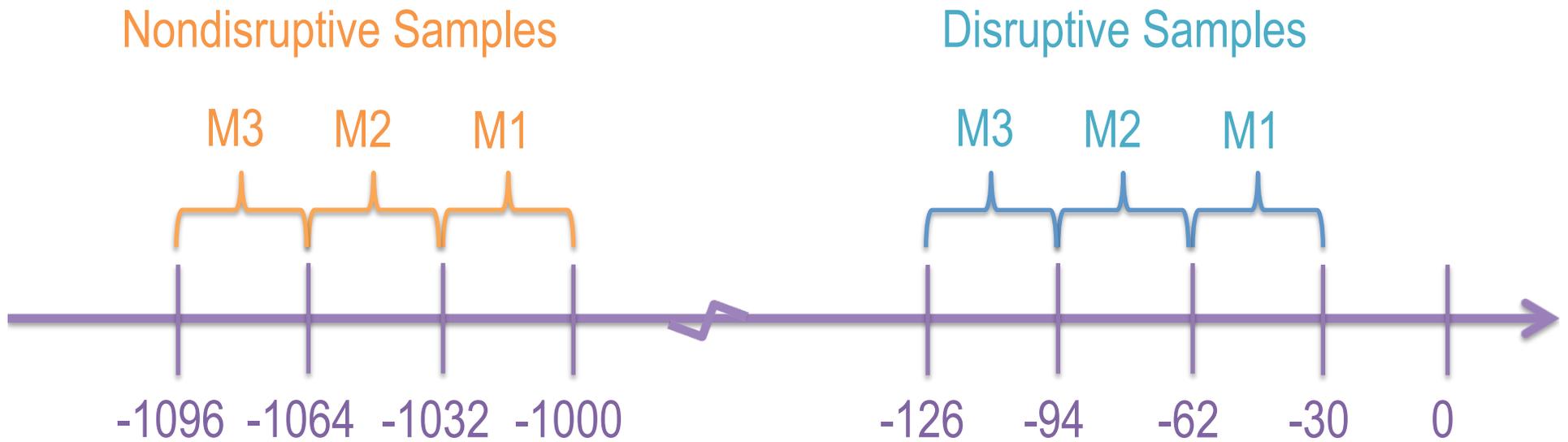
**Visible light
from colder
plasma in
divertor/
wall regions**



Preliminary Work at PPPL

- Gained access to JET database (MDSplus)
- Extracted signal & video
- Acquired and implemented SVM framework from APODIS
- Rewrote development framework to be self-contained within Matlab 2014, resulting in:
 - *100x speedup over using LIBSVM by avoiding excessive I/O*
 - Simple training / testing reduced from 85 min to < 1 min

Multi-tiered SVM Training

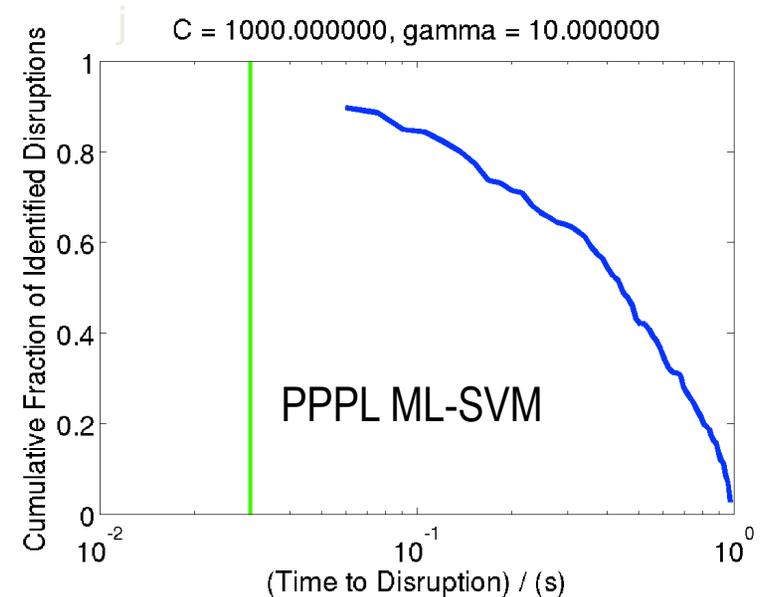
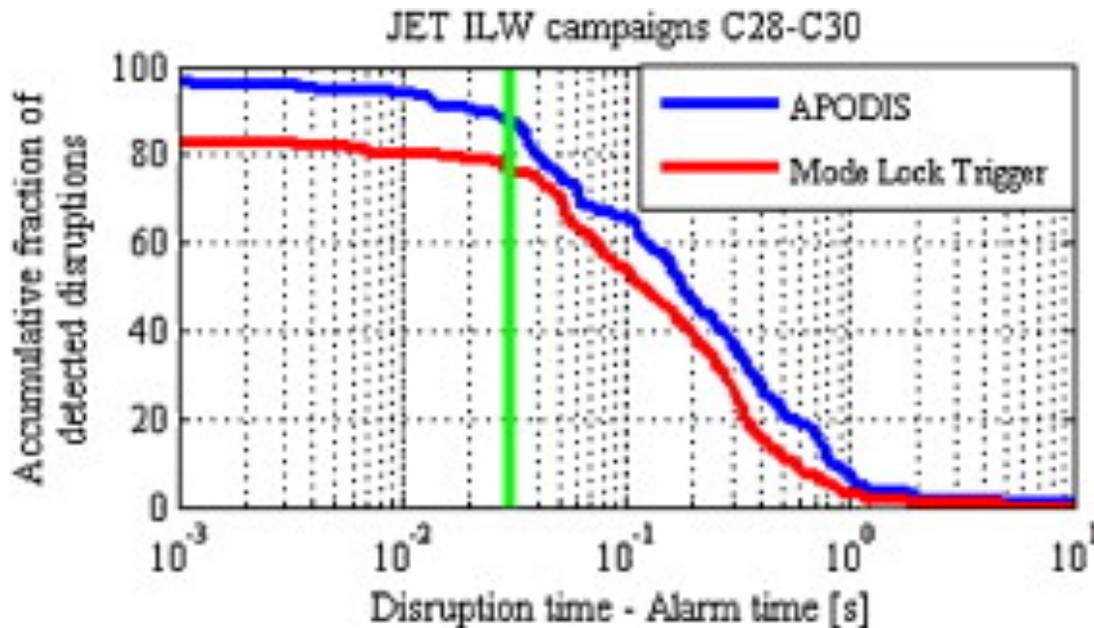


Times given as $t - t_0$ in milliseconds

RECENT RESULTS for JET ILW Disruption Data: Comparison of Results from PPPL ML-SVM Analysis with APODIS

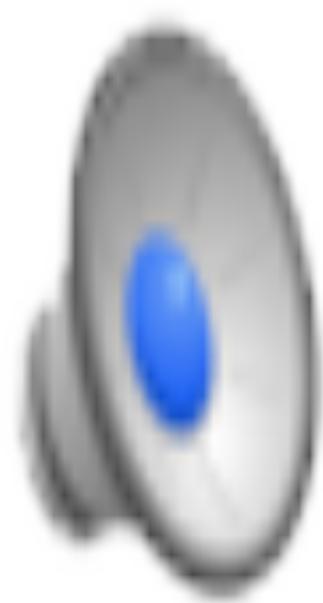
30 ms before disruption (Ref.-- P. DeVries – ITER disruption prediction requirements → mitigation trigger time > 30 ms)

APODIS predicted rate of 87.5% while PPPL ML-SVM gives 89.8%



- APODIS trained on 738 disruptive and 2,035,000 non-disruptive samples
- PPPL's version of ML-SVM trained on 975 disruptive and 975 non-disruptive samples

Projecting 14D space (7 signals x 2) into 3D space
to develop SVM Classifiers → movie shows
separability of Disruptive from Non-Disruptive Data:



DA (Deterministic Annealing) Method

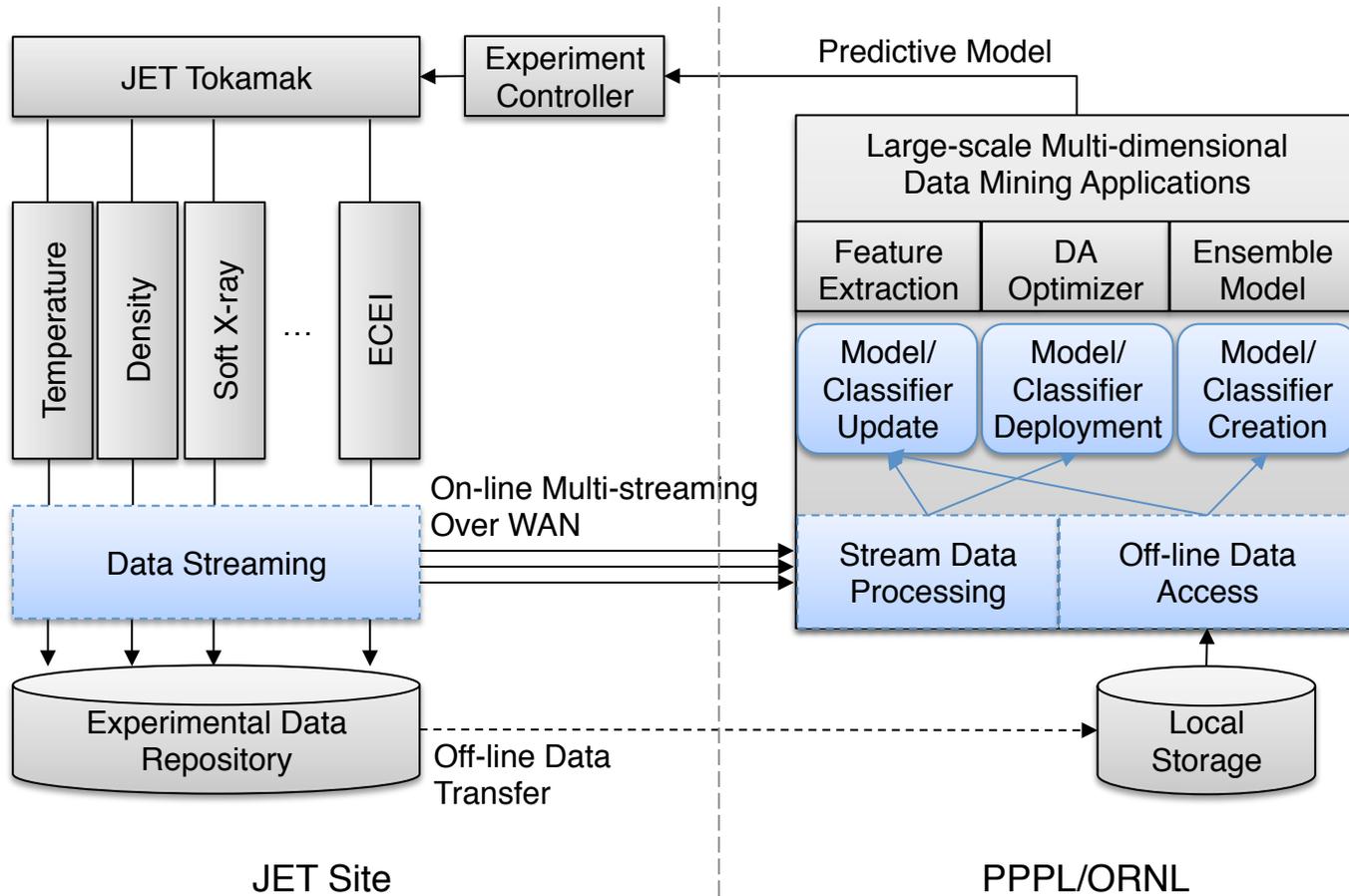
Jong Choi, ORNL

Generative Topographic Mapping (GTM) using Deterministic Annealing (DA)

References:

- J. Y. Choi, et al. Science Direct, Proc. Computer Science 00, 1-10 (2010)
- Geoffrey Fox, et al., Parallel Processing Letters, May 17, 2013.

Fusion Data Mining Diagram



Summary

- **Fusion Energy Mission Relevance:**

- Goal of Magnetic Fusion Energy goal is demonstrating the *scientific & technical feasibility of delivering Fusion Power*
- Most critical associated problem is to *avoid/mitigate large-scale major disruptions*

- **Relevance to HPC:**

- *New focus* on development of large-data-driven “**machine-learning**” **statistical methods** as alternative/complement for conventional “hypothesis-driven/first principles” predictive methods

- **Associated Challenge:**

- *Significant improvements over zero-D SVM-based machine-learning capabilities to achieve >98% success rate with portability of software to ITER via enhanced physics fidelity (capturing multi-D) and execution time (moving beyond clusters to Leadership Class Facilities).*